

Lab #:

Using Free-Body Diagrams to Apply Newton's Laws

Each exercise worth 1 point except for 10,12,17 which are worth 2 points

Purpose of the lab: To learn to analyze an object's motion by isolating it and showing all forces acting on it.

Note: This is a take-home exercise—due at the start of your Lab 5 session.

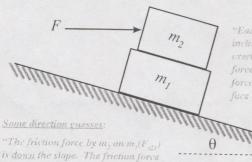
<u>Materials needed</u>: A ruler or other straight edge may be handy. No extra paper is needed—write on the pages provided.

Directions: For each situation,

- 1. Using the given sketch (or create your own, as necessary), identify the nature and direction of all forces acting on the mass. If you don't know a direction, make your best guess.
- 2. Choose (and indicate) your coordinate system. If the mass is known to be accelerating in a certain direction, choose a coordinate system so that one of its axes aligns with the direction of that acceleration.
- 3. Draw a free-body diagram (FBD) showing all forces acting on the object. Label all forces with variables, not numbers. Draw all force vectors with their tails beginning at the same place (use just a tiny box to represent the object in question—regardless of the actual shape of the object). Indicate any reference angles that will be used to resolve a vector into its x- and y- components. (Do not draw any acceleration vector on the free-body diagram. This is a force diagram.)
- 4. Use Newton's 2nd Law to write equations for x- and y- directions. You do not need to solve these equations. In writing each equation, don't plug in any numbers except zero. Just sum the forces on the left-hand side. Write the x- and y- components of a vector in terms of its magnitude and an angle. Also, use the expressions you know for weight $(W = mg \text{ or } F_G = Gm_1m_2/r^2)$ and friction $(F_s^{max} = \mu_s F_N \text{ or } F_k = \mu_k F_N)$ whenever applicable.
- 5. Some situations involve more than one object. Do the above four steps separately for each object.

EXAMPLE: Masses m_1 and m_2 are stacked and accelerating together down the inclined surface. Force F is horizontal. The coefficient of kinetic friction between the surface and m_1 is μ_k . The coefficient of static friction between m_1 and m_2 is μ_s . Analyze all forces on each mass.

"Gravity exerts a vertical weight force on each mass."



"Each surface (the incline, m, and m) exerts a normal force and a friction force on any surface it touches."

coord. axes

F_R F₈₂₁

x-analysis

$$\Sigma F_x = m_I a_x$$

by the surface on m, is up the stope."

$$F_{s21} + W_{1x} - F_k = m_1 a_x$$

$$\mu_s F_{N2I} + m_I g \sin\theta - \mu_k F_N = m_I a$$

v-analysis

$$\Sigma F_y = m_l a_y$$

$$F_N - F_{N2I} - W_{Iy} = m_I a_y$$

$$F_N - F_{N21} - m_1 g \cos\theta = 0$$

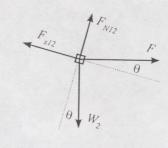
The three equation forms shown are <u>required</u> for each analysis. Notice how you add more detail to the equation in each form. And notice how your choice of coordinate system here allows you to write a_x as just a (the <u>total</u> acceleration), because a_y is 0.

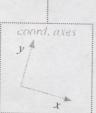
Notation examples:

 F_{NI2} is "the normal force exerted by m_1 on m_2 .

 F_{s21} is "the static friction force exerted by m_2 on m_1 .

 F_k is "the kinetic friction force exerted by the surface (on the object it's touching)."





x-analysis

$$\Sigma F_x = m_2 a_x$$

$$F_x + W_{2x} - F_{S12} = m_2 a_x$$

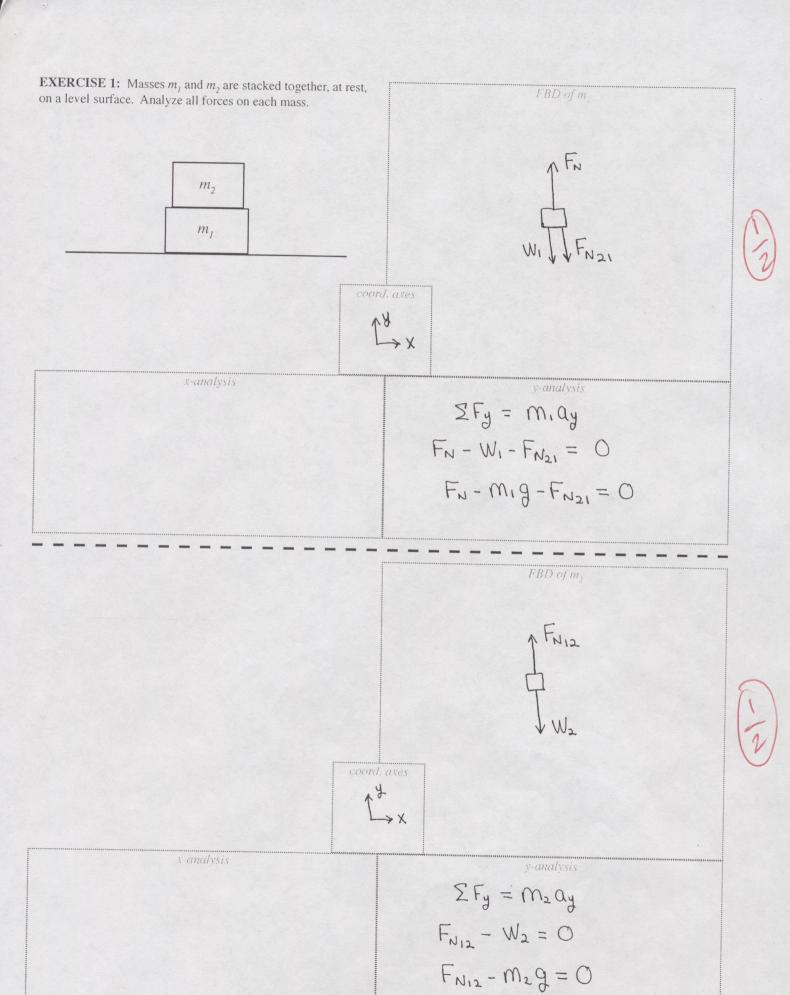
$$F\cos\theta + m_2 g\sin\theta - \mu_S F_{NI2} = m_2 a$$

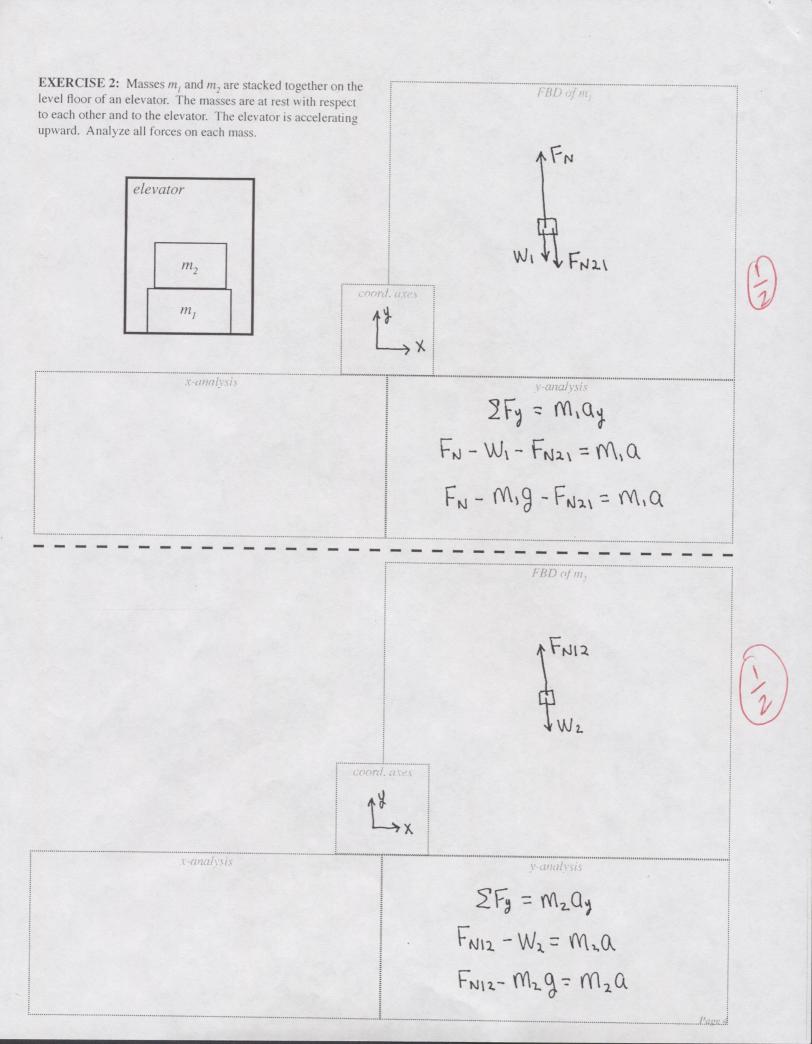
y-analysis

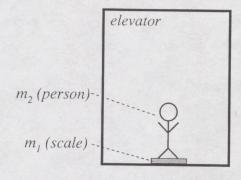
$$\Sigma F_{y} = m_{2}a_{y}$$

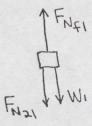
$$F_{N12} + F_{y} - W_{2y} = m_{2}a_{y}$$

$$F_{N12} + F\sin\theta - m_2g\cos\theta = 0$$









x-analysis

v-analysis

$$\Sigma F_y = m_1 a_y$$

 $F_{N_{21}} + W_1 - F_{N_{f_1}} = m_1 a$
 $F_{N_{21}} + m_1 g - F_{N_{f_1}} = m_1 a$

 $FBD \ of \ m$,



coord. axe.

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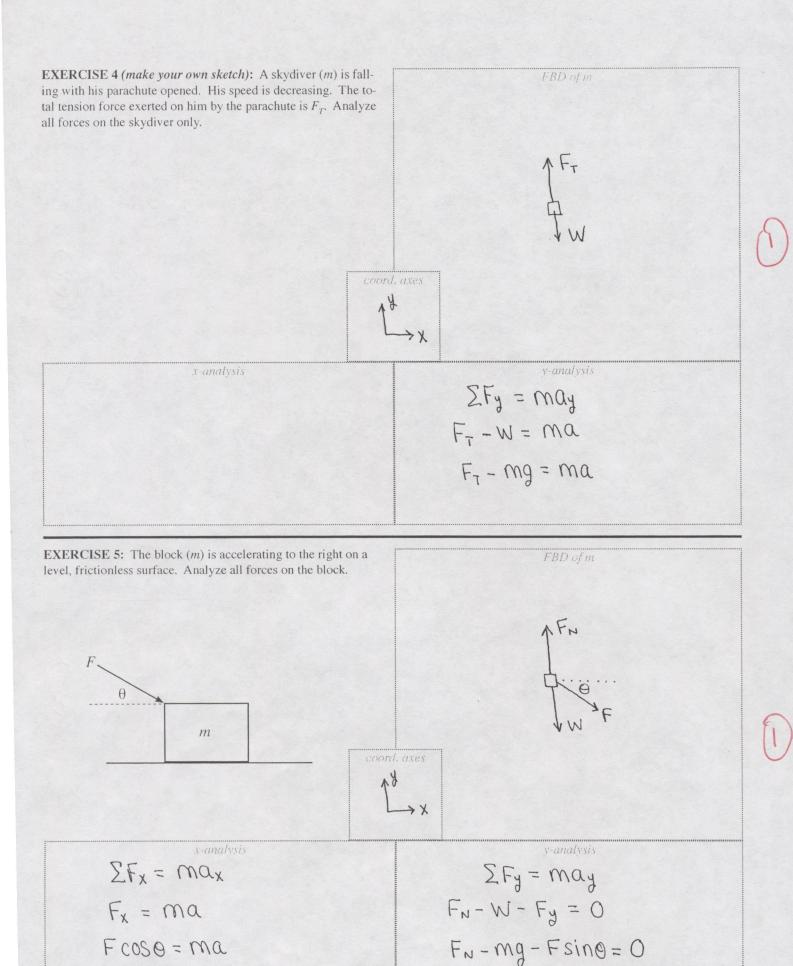
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$$\Sigma F_{y} = m_{1}a_{y}$$

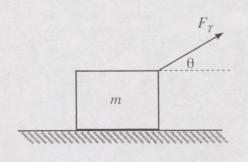
 $W_{2} - F_{N_{12}} = m_{1}a$
 $m_{2}g - F_{N_{12}} = m_{1}a$

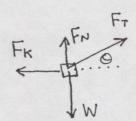














v onalveic

$$\Sigma F_{x} = m\alpha_{x}$$

$$F_{Tx} - F_{k} = p\lambda = m\omega_{y} = 0$$

$$F_{7} \cos \theta - \mu_{k} F_{N} = |\Omega| + m\omega_{k} = 0$$

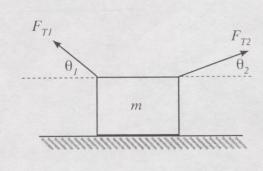
$$\Sigma F_y = may$$

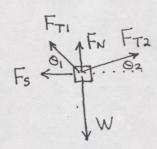
$$F_N + F_{Ty} - W = 0$$

$$F_N + F_T \sin \theta - mg = 0$$

EXERCISE 7: The block (m) is at rest on a level surface with friction (μ_s) . Analyze all forces on the block.







 $\overset{\text{coord. axes}}{\longrightarrow} X$

-analysis

v-analysis

$$\Sigma F_{x} = M\alpha_{x}$$

$$F_{T_{2}x} - F_{T_{1}x} - F_{s} = 0$$

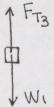
$$F_{T_{2}} \cos \alpha_{2} - F_{T_{1}} \cos \alpha_{1} - F_{s} = 0$$

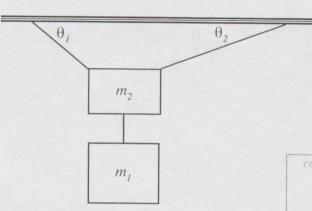
$$\Sigma F_y = may$$

$$F_{T_1y} + F_N + F_{T_2y} - W = 0$$

$$F_{T_1} \sin \theta_1 + F_N + F_{T_2} \sin \theta_2 - mg = 0$$

Page ?





coord. axes \uparrow^{y} \times

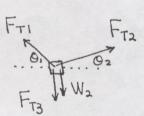
x-analysis

y-analysis

$$\Sigma F_y = ma_y$$

 $F_{T3} - W_1 = 0$
 $F_{T3} - m_1 g = 0$

FBD of m,



coord. axes

x-analysis

EFX = max

FT2X - FTIX = O

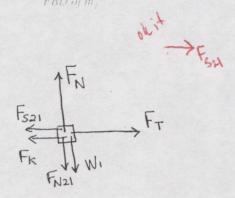
 $F_{T_2}COS\theta_2 - F_{T_1}COS\theta_1 = O$

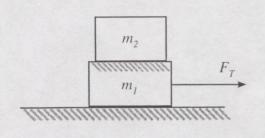
v-analysis

$$\Sigma F_y = may$$
 $F_{T_1y} + F_{T_2y} - F_{T_3} - W_2 = 0$
 $F_{T_1} sin \theta_1 + F_{T_2} sin \theta_2 - F_{T_3} - m_2 g = 0$

(1/2)

(1/2)





coord. axes

x-analysis

y-analysis

FBD of m_2



coord, axes \uparrow^{\downarrow} \downarrow \downarrow

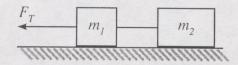
x-analysi:

v-analysis

Dano (

EXERCISE 10: Blocks m_1 and m_2 are accelerating together to the left on a level surface that has friction (μ_k) . The blocks are connected by a string of negligible mass that remains taut at all times. Analyze all forces on each block.

FBD of m



coord, axes

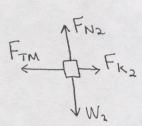
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x-analysis

$$\Sigma F_x = M, \alpha_x$$

v-analysis

FBD of m,

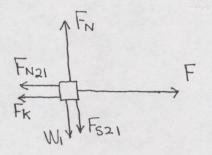


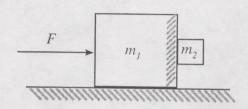
coord are

× 14

v...malucie

 $\Sigma F_{y} = m_{2} \alpha_{y}$ $F_{N_{2}} - W_{2} = 0$ $F_{N_{2}} - m_{2} q = 0$





14 X

x-analysis

y-analysi.

FBD of m,



coord, axes

1^y x

x-analysis

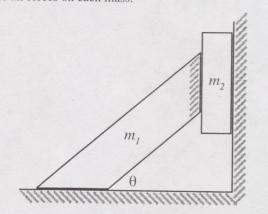
$$\Sigma F_X = M_2 Q_X$$

v-analysis

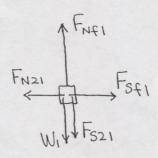
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EXERCISE 12: Masses m_1 and m_2 are not attached to one another, but they are at rest in the positions shown. The level floor and the vertical wall offer static friction μ_{s1} and μ_{s2} , respectively. There is also static friction (μ_{s3}) between the two masses. Analyze all forces on each mass.



FBD of m



coord, axes

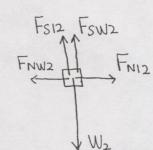
-analysis

$$2F_x = m_1 a_x$$

y-analysis

$$\Sigma F_y = m.a_y$$

FBD of m_2



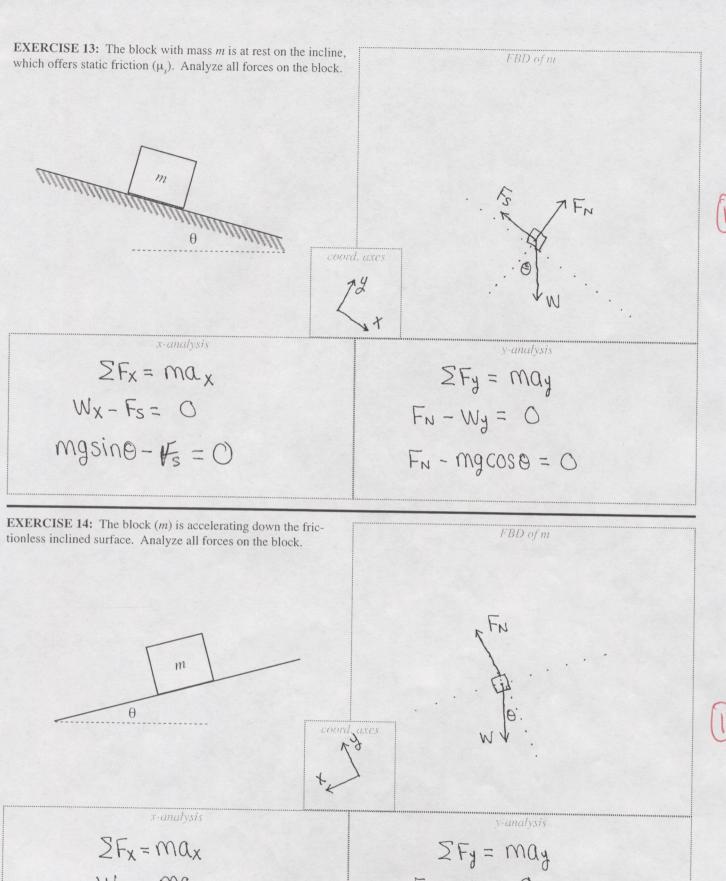
coord. axes \downarrow

-analysis

$$\Sigma F_X = m_2 \alpha_X$$

v-analysis

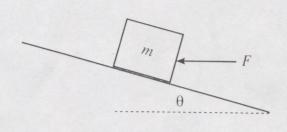
$$F_{S12} + F_{SW2} - W_2 = 0$$

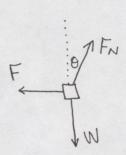


 $\Sigma F_X = ma_X$ $W_X = ma$ mgsin0 = ma $\Sigma F_y = may$ $F_N - Wy = 0$ $F_N - mgcose = 0$

EXERCISE 15: The block with mass *m* is moving up the frictionless incline at a constant velocity. Analyze all forces on the block.







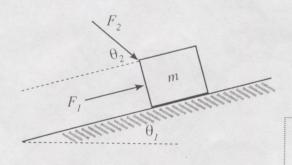
x-analysis

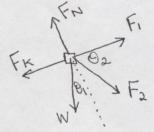
$$\Sigma F_{x} = m \alpha_{x}$$

y-analysis

EXERCISE 16: The block (m) is accelerating up the inclined surface. The coefficient of kinetic friction between the block and the incline is μ_k . Analyze all forces on the block.

FBD of m





x-analysis

$$\Sigma F_x = max$$

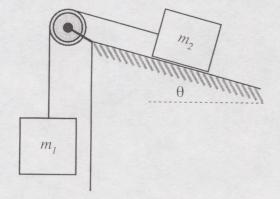
$$F_1 + F_{2x} - F_k - W_x = ma$$

$$F_1 + F_2 \cos \theta_2 - \mu_k F_N - mg \sin \theta_1 = ma$$

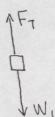
v-analysis

$$F_N - W_y - F_{2y} = 0$$

EXERCISE B: Blocks with masses m_1 and m_2 are connected by a string (with negligible mass) that passes over a frictionless pulley. The coefficient of kinetic friction between m_2 and the incline is μ_k . The masses are accelerating as one unit—the string is taut at all times. Analyze all forces on each mass.



FBD of m



coord, axes

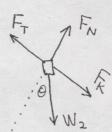
x-analysis

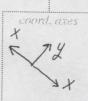
v-analysis

$$\Sigma F_y = m_1 a_y$$

 $W_1 - F_T = m_1 a$
 $m_1 g - F_T = m_1 a$

FBD of m_2





-analysis

$$\Sigma F_X = M_2 \alpha$$

$$F_T - F_K - W_{2X} = M_2 \alpha$$

v-analysis

$$\Sigma F_y = m_z \alpha_y$$

$$F_N - W_{2y} = 0$$

$$F_N - m_2 g \cos \theta = 0$$